

Computing modular Galois representations

An implementation of the finite field approach

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Introduction

Let X be a (smooth, complete, geometrically connected) curve of genus g over a finite field k .

Consider the Picard group

$$\begin{aligned}\mathrm{Pic}^0 X &= \{\text{divisors of degree } 0\} / \{\text{principal divisors}\} \\ &= \{\text{line bundles of degree } 0\} / \cong.\end{aligned}$$

This is also the group of k -rational points of the Jacobian variety J of X , which is an Abelian variety of dimension g over k .

Goal: compute efficiently in $\mathrm{Pic}^0 X = J(k)$ if g is large.

What we want to do

- Represent X , divisors on X and elements of $J(k)$
- Perform group operations in $J(k)$
- Pick random elements of $X(k)$ and $J(k)$
- Evaluate the Frobenius automorphism of $J(k')$ for finite extensions k'/k
- Evaluate Kummer maps $J(k)/nJ(k) \rightarrow J(k)[n]$
- Evaluate Frey–Rück (Tate) pairings $J(k)[n] \times J(k)/nJ(k) \rightarrow \mu_n(k)$

Using these operations, one can find a basis of $J(k)[l]$, with $l \neq \text{char } k$ a prime number, in time polynomial in g , $\log \#k$ and l , provided we know the zeta function of X .

Possible approaches

Various approaches have been developed for computing in $\text{Pic}^0 X$, based on different ways to represent X and divisors on it:

- (1) as a (ramified) covering of \mathbf{P}^1 ;
- (2) as a curve in \mathbf{P}^2 (necessarily singular for general X);
- (3) by an embedding into a projective space of relatively high dimension.

We will only consider the third approach. There exist efficient algorithms, due in the first place to K. Khuri-Makdisi (2004) and extended in my thesis (2010).

Khuri-Makdisi's methods are tailored for modular curves. For example, if $n \geq 5$ the required representation of $X_1(n)$ over k can be obtained from a basis of q -expansions for the space of modular forms of weight 2 for $\Gamma_1(n)$ over k .

How to represent X

Following Khuri-Makdisi, we choose a line bundle \mathcal{L} on X with

$$\deg \mathcal{L} \geq 2g + 1.$$

Let $\Gamma(X, \mathcal{L})$ denote its space of global sections. (For us, this is just a space of modular forms.)

Besides $\Gamma(X, \mathcal{L})$, we store the spaces $\Gamma(X, \mathcal{L}^i)$ for $1 \leq i \leq 7$ and the multiplication maps between them.

This gives a representation of X in terms of linear algebra.

Remark: We never need to write down equations (although they are implicit in the data and can be extracted if needed).

How to represent points

We represent points on X by hyperplanes in $\Gamma(X, \mathcal{L})$: to $x \in X$ we associate the subspace

$$V_x = \{f \in \Gamma(X, \mathcal{L}) \mid f(x) = 0\} \subset \Gamma(X, \mathcal{L}).$$

This construction gives a projective embedding

$$X \hookrightarrow \mathbf{P}\Gamma(X, \mathcal{L})$$

$$x \mapsto V_x.$$

Remark: after choosing a basis (f_0, \dots, f_n) of $\Gamma(X, \mathcal{L})$, this embedding looks like

$$X \hookrightarrow \mathbf{P}_k^n$$

$$x \mapsto (f_0(x) : f_1(x) : \dots : f_n(x)).$$

However, we prefer to represent x by the hyperplane $V_x \subset \Gamma(X, \mathcal{L})$ rather than by a vector.

How to represent divisors

Similarly, we represent effective divisors D on X by subspaces of the form

$$\begin{aligned} V_D^i &= \Gamma(X, \mathcal{L}^i(-D)) \\ &= \{f \in \Gamma(X, \mathcal{L}^i) \mid f \text{ vanishes on } D\} \end{aligned}$$

for i large enough such that $\deg \mathcal{L}^i(-D) \geq 2g + 1$.

Remark: This comes down to embedding the d -th symmetric power $\text{Sym}^d X$ (variety of effective divisors of degree d) into the Grassmannian variety of subspaces of codimension d in $\Gamma(X, \mathcal{L}^i)$:

$$\text{Sym}^d X \hookrightarrow \text{Gr}^d \Gamma(X, \mathcal{L}^i).$$

Computing with divisors

Khuri-Makdisi's algorithms are based on two fundamental results:

Lemma (multiplication): We can compute V_{D+E}^{i+j} from V_D^i and V_E^j by

$$\begin{aligned} V_{D+E}^{i+j} &= V_D^i \cdot V_E^j \\ &= \text{span}\{vw \mid v \in V_D^i, w \in V_E^j\} \subset \Gamma(X, \mathcal{L}^{i+j}) \end{aligned}$$

Lemma (division): We can compute V_D^i from V_{D+E}^{i+j} and V_E^j by

$$\begin{aligned} V_D^i &= V_{D+E}^{i+j} \div V_E^j \\ &= \{v \in \Gamma(X, \mathcal{L}^i) \mid vV_E^j \subseteq V_{D+E}^{i+j}\}. \end{aligned}$$

These allow us to add and subtract divisors and to test for linear equivalence.

Computing in the Jacobian

Write

$$d = \deg \mathcal{L} \quad (\geq 2g + 1).$$

Elements of $J(k)$ are represented by effective divisors of degree d as follows:

$$\{\text{effective divisors of degree } d \text{ on } X\} \rightarrow J(k)$$

$$D \mapsto \text{isomorphism class of } \mathcal{L}(-D).$$

Addition and negation in J can be built up from $0 \in J(k)$ and the operation

$$\text{addflip: } (x, y) \mapsto -x - y.$$

Let $x, y \in J(k)$ be represented by effective divisors D, E . Then $-x - y$ is represented by any effective divisor F such that $\mathcal{L}^3(-D - E - F) \cong \mathcal{O}_X$.

Picking random points and divisors

We would like to pick uniformly random elements from the finite sets $X(k)$ and $J(k)$.

Algorithm: Choose a uniformly random hyperplane H in $\mathbf{P}\Gamma(X, \mathcal{L})$. Compute the set $\{x_1, \dots, x_r\}$ of rational points in $H \cap X$. With probability $r/\deg \mathcal{L}$, pick one of the x_i ; else start over.

Using a similar approach, we can pick uniformly random prime divisors on X .

Uniformly random effective divisors of a given degree m can be built up from prime divisors as follows. First select the “decomposition type” (degrees and multiplicities of prime divisors) of a uniformly random effective divisor of degree m using the zeta function of X . Then pick a uniformly random such divisor having this decomposition type.

Further operations

If k' is a finite extension of k , we can compute the Frobenius map

$$F: J(k') \xrightarrow{\sim} J(k')$$

by applying the $\#k$ -th power map on matrix entries with respect to k -bases.

If n is coprime to $\text{char } k$ and $J[n]$ is k -rational, we can compute the Kummer isomorphism

$$K: J(k)/nJ(k) \xrightarrow{\sim} J(k)[n]$$

coming from Galois cohomology of $0 \rightarrow J[n] \rightarrow J \xrightarrow{n} J \rightarrow 0$. Under the weaker assumption that k^\times contains the n -th roots of unity, we can compute the Frey–Rück (Tate) pairing

$$[\ , \]_n: J(k)/nJ(k) \times J(k)[n] \rightarrow \mu_n(k).$$

(Based in part on work of Couveignes, transferred to our setting.)

Application: computing modular Galois representations

Let f be a normalised Hecke eigenform, let K be the number field generated by the coefficients of f , let λ be a finite place of K with residue field \mathbf{F}_λ .

There are associated semi-simple Galois representations

$$\rho_{f,\lambda}: \text{Gal}(\overline{\mathbf{Q}}/\mathbf{Q}) \rightarrow \text{GL}_2(K_\lambda),$$

$$\bar{\rho}_{f,\lambda}: \text{Gal}(\overline{\mathbf{Q}}/\mathbf{Q}) \rightarrow \text{GL}_2(\mathbf{F}_\lambda).$$

We want to compute $\bar{\rho}_{f,\lambda}$ in the sense of giving a finite Galois extension L/\mathbf{Q} together with an embedding $\text{Gal}(L/\mathbf{Q}) \hookrightarrow \text{GL}_2(\mathbf{F}_\lambda)$.

If $\bar{\rho}_{f,\lambda}$ is irreducible, then after twisting it occurs in $J_1(n)[l](\overline{\mathbf{Q}})$ for a suitable n , where $l = \text{char } \lambda$ and $J_1(n)$ is the Jacobian of $X_1(n)$. This allows us to reduce the problem of computing $\bar{\rho}_{f,\lambda}$ as follows: given a maximal ideal \mathfrak{m} of the Hecke algebra acting on $J_1(n)$, with residue field \mathbf{F} , compute $J_1(n)[\mathfrak{m}]$.

(Project of Couveignes, Edixhoven et al.; “Schoof-like” algorithm.)

Application: computing modular Galois representations

We choose a suitable embedding of \mathbf{Q} -schemes

$$\iota: J_1(n)[\mathfrak{m}] \hookrightarrow \mathbf{A}_{\mathbf{Q}}^1.$$

Then $\text{im } \iota$ is defined by a polynomial over \mathbf{Q} ; the induced \mathbf{F} -vector space scheme structure on $\text{im } \iota$ is also given by polynomials over \mathbf{Q} .

Strategy for computing $J_1(n)[\mathfrak{m}]$: find these polynomials either numerically over \mathbf{C} or modulo p for sufficiently many small prime numbers p , and then reconstruct $\text{im } \iota$ over \mathbf{Q} .

Remark: to know how much precision/how many p we need to ensure correctness, one needs a bound on the heights of the coefficients of the polynomials. Such a bound can be derived (with a lot of work) if one chooses ι carefully.

PARI implementation of the finite field approach (work in progress)

The program (ca. 5700 lines of C code using the PARI library) consists of four modules:

- `libpari-extra` – various utility functions: linear algebra, finite algebras, extensions of finite fields (small characteristic, i.e. F_1 and $F_1[x]$)
- `modular` – a toy implementation of modular symbols. Hopefully this will soon be switched to the new PARI `ms*` functions (main new ingredient needed: modular symbols for $\Gamma_1(n)$).
- `jacobian` – general curves over finite fields, Jacobians, operations on them (using Khuri-Makdisi's algorithmic representation)
- `modgalrep` – modular curves and Jacobians; Galois representations

Linear algebra (over finite fields) is currently the main bottleneck.